Space Wrench

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Design a printable wrench to tighten a fastener that is partially blocked by an access panel

Problem Statement



Ideation





 Design for ergonomic tool use, therefore hand grip orientation is parallel to wrench body

Design Goals



#1

Separate handle with threads

But,

Issues with threads can lead to mechanical failure

Concept Sketches











- Single body with filleted corners to reduce stress concentrations
- Filleted body also improves usability and aesthetics

Concept Sketches







Head & Handle

- Ergonomic handle for ease of use
- Tapered head and body to improve mass efficiency

Concept Sketches





Design Iterations





Thickness of wrench is 0.22" to match nut height

But,

- Lack of ergonomic form
- Arbitrary dimensioning
- No tolerance

First Iteration



Ergonomics

Hand span when gripping:



2.5" - 3.0"





Handle length:

2.7180"

- Length and width of handle to comfortably fit hand
- Medium handle length to minimize overhang







 Length of head is 1.442" and vertical height is 1.450" to avoid interference with the test rig

Dimensions





- Fabrication clearance of 0.005"
- Additional tolerance of 0.015"
- Total tolerance : 0.020"

Tolerance



Ergonomic handle

• Well dimensioned

But,

- Aesthetic extrusion on handle diminishes comfortable use
- Inconsistent chamfer

Second Iteration







- Well dimensioned
- Ergonomic form
- Consistent
 chamfering also
 improves aesthetics

Final Design



Functionality



Steps

Insert with wrench head
 vertical (facing ground)

- ✓ Once in test rig, rotate
 wrench through ~90°
- ✓ Take out and repeat



One full rotation is ~ 4 turns

Functionality

Material Analysis & Printability





Source : matterhackers.com

PLA

Good because:

- Has medium impact strength
- Has medium stiffness

benefitting the space wrench design because:

- Resists mechanical failure
- Able to withstand sufficient torque

Material Analysis

Source: imakr.com

ABS

- Higher tensile strength
- Higher impact resistance
- therefore, it would be a better material because:
- Greater resistance against mechanical failure
- Able to withstand higher torque
- Good for functional prototypes

Alternative Material

- Support wrench overhangs, which are equal or greater than 45°
- Brim for sufficient adhesion and minimizes warping
- Print time is 1 hour 41 min

Printability

minutes	•
Save to File	
minutes	Ð
Save to File	

Since FDM, flat (in x-y) orientation is best to:

- maximize strength
- reduce warping of overhangs
- minimize print time and material use

Additionally,

Filleting corners of wrench provides strength for build

Printability

Final Product

Final Product

I approached the problem with a keen focus on usability during the first iteration of my designs. As a result, I honed in on features (such as the form of the handle) that would improve the user experience. In the process, I neglected to focus on key aspects that would be integral to the functionality, such as the wrench's dimensions.

In subsequent iterations, I began making revisions to improve functionality and leverage the capabilities of additive manufacturing. In the process, I relied upon mechanical design concepts. I applied heuristics about the locations of high stress concentrations, such as corners, and added fillets. Additionally, I minimized the surface area to improve the overall mass efficiency of my wrench. Furthermore, I oriented my part to leverage support and adhesion types that would strengthen my wrench during build.

Throughout this process, I learned the importance of integrating my technical and analytical intuitions into my human-centered design process — the two processes should work in tandem to create robust, user-centered final products. This is a lesson I aim to strengthen throughout my engineering career.

- Sketching + Cataloguing : 1.5 hr
- CAD: 5hrs
- Documentation: 5 hrs

Total time spent was 11.5 hours

Process Reflection

One of my primary focuses was ensuring that my wrench was handle ergonomic. The orientation of the handle delivered a pleasant user experience as it was easy to apply torque without having to orient my hand in an awkward position. Further wrench iterations would have included a handle with rounded edges for increased usability. Additionally, the application of torque was sufficient to turn the nut. However, because of a failure to leave enough clearance at the interface between the vertical segment of the wrench body and the curved inner surface of the test rig, it was challenging to re-position the wrench head in order to tighten the nut. This resulted in it taking a longer time for me to tighten the nut (as evidenced in my demonstration video). This was a lesson to ALWAYS ensure you have enough clearance!:)

